



Wireless Telemetry + CAR
Argus 682

"We watch so you don't have to."

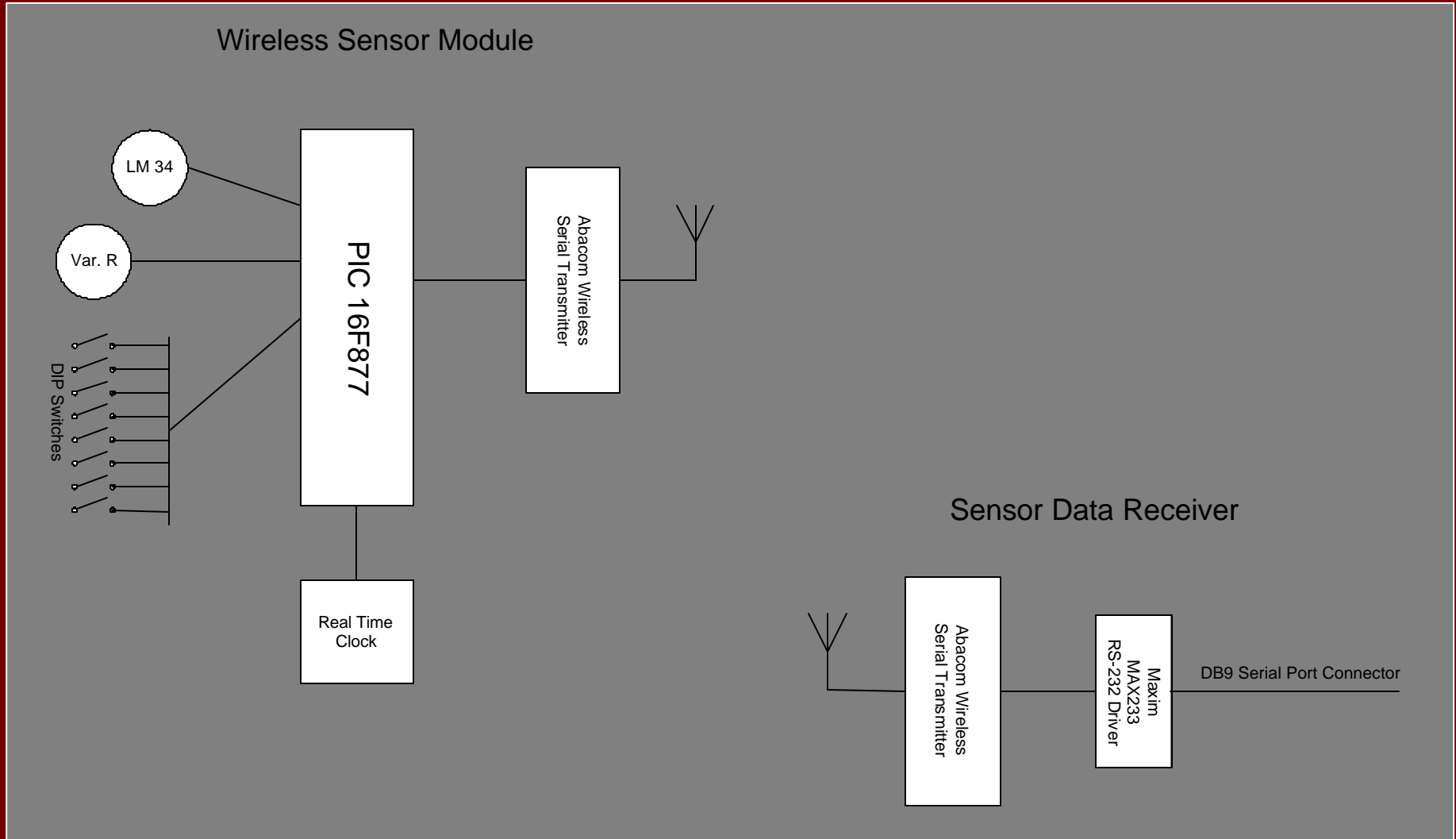
Midterm Presentation

Tuesday, February 05, 2002

Who are we?

- Nate Distel: MCU, Sensors
- Solomon Gibbs: Linux, Net Code
- Max Vilimpoc: Serial Code, Linux
- Aravind Mikkilenini: Linux, Serial Code
- Rich Fouts: Wireless Comm.
- Mike Volkerding: Sensors, Power
- Pat Stemen: MCU, Organization

Graphical View:



Project Basics

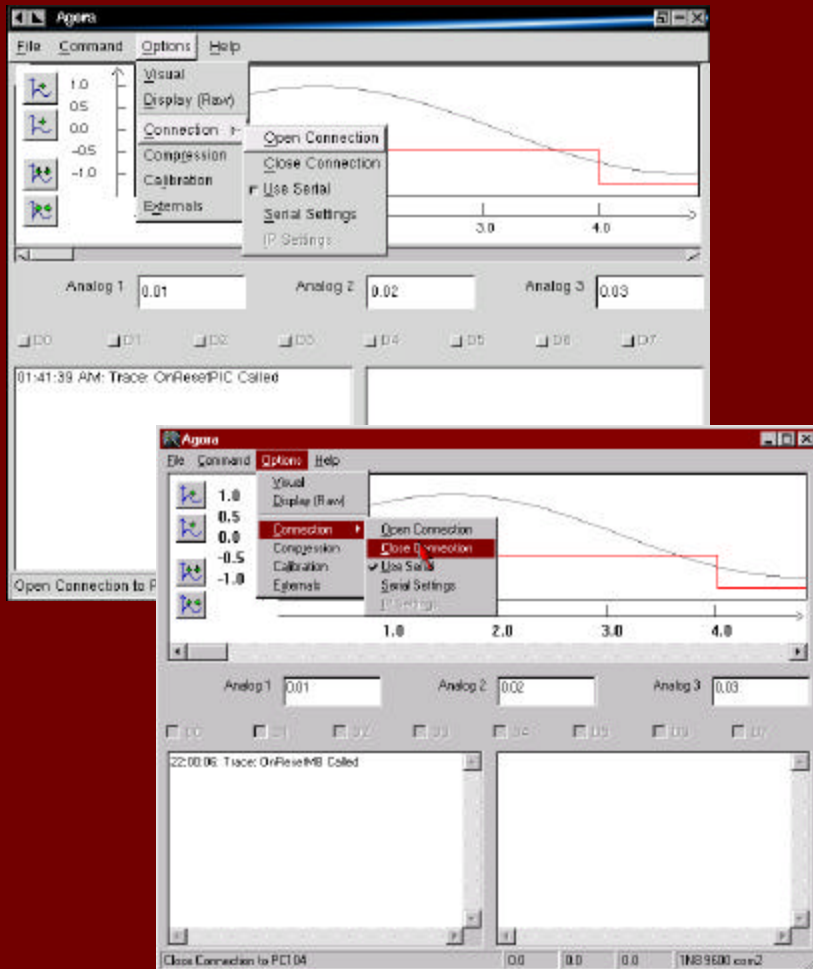
- Start With Basics:
 - Use PIC MCU with onboard A/D
 - Temperature, Resistance sensing
 - Use Digital I/O on PIC
 - Digital On / Off – different uses depending on platform
 - Simple Wireless Interface
 - Abacomm 433Mhz Wireless Modules (9600bps / Simplex)

Project Extras

- Use basics to develop unique features
 - User Interface Development for various platforms
 - Work with unique sensors (accelerometers)
 - Real-Time Clock Module
 - Variable-Length Packet Data

User Interface

Runs Under GTK, Motif, Win32

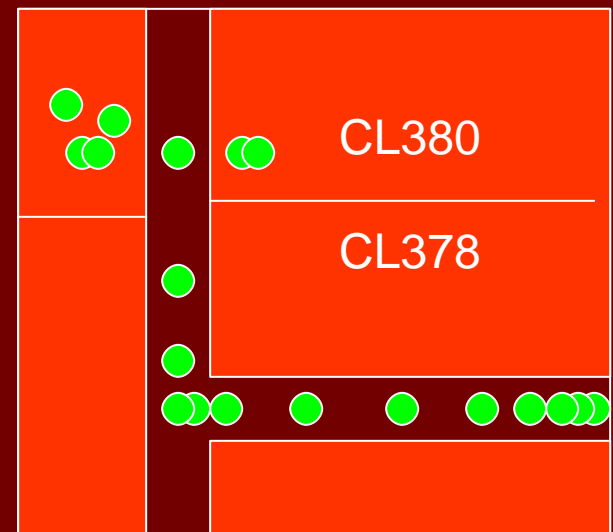
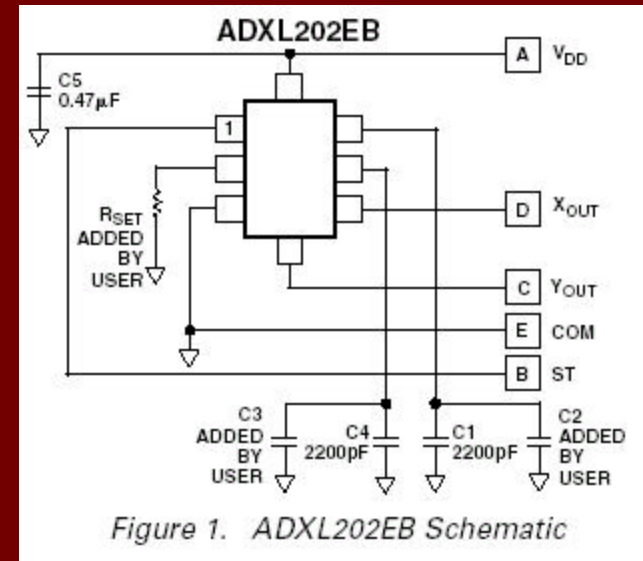


- Written in Cross-Platform C++ (wxWindows)
- Connects to Remote host via Serial or IP
- Currently Working on:
 - Improving Parser
 - Writing a Custom Data Plotting Widget
- Plan To Add:
 - Remote Control Functions
 - Data Logging

Sensors / Accelerometer

■ Analog Devices ADXL202

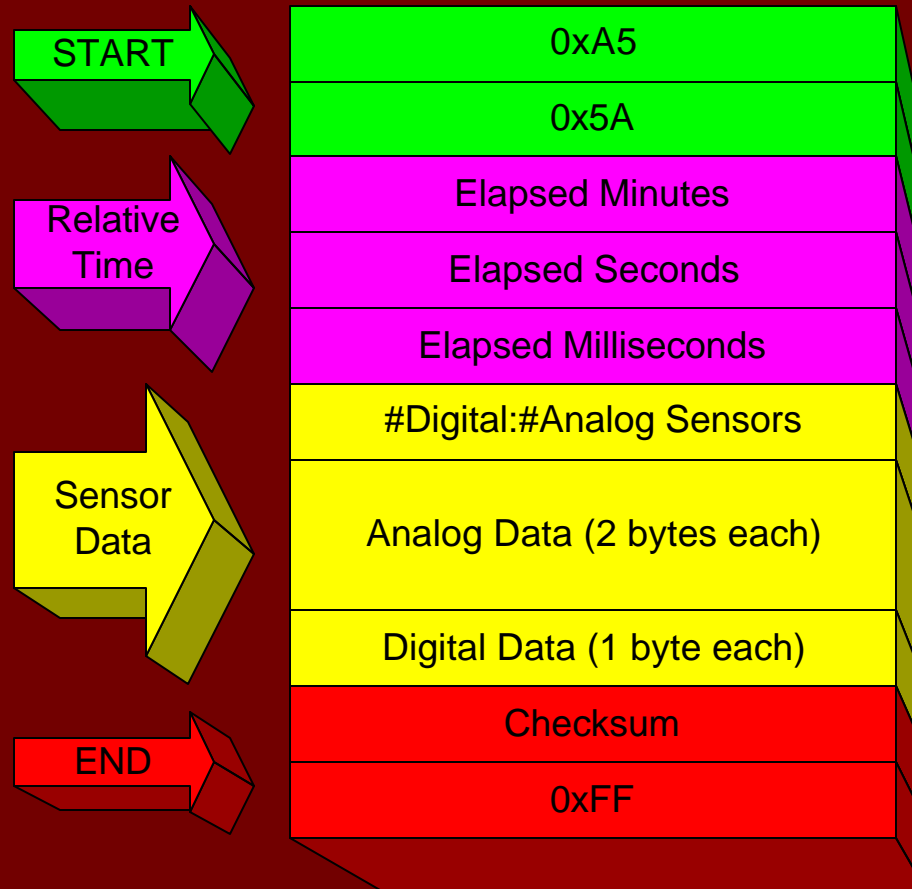
- 2-axis, $\pm 2g$ sensor sensitive enough to measure gravity.
- Integration of this module will provide:
 - Acceleration
 - Velocity
 - Position
- Possible applications include:
 - Realtime mapping of operating environment relative to start position (Caldwell Labs)
 - Absolute position mapping with GPS interface for initial location reading



Wireless Communications

- TXM Series transmitter and SILRX Series Receiver
- FM Range
- 433 MHz
- Supply Voltage 4.5v – 9v
- Small Size
- Easy to use!!

Data Packets



Moving Forward

- Integrate Accelerometer from Max's 683 Research Project
- Looking into solar based power supply
 - Use solar panel to charge batteries for constant power requirements
- Researching other methods to increase wireless range
 - Goal: Max range 250 feet